

A cascaded H-bridge multilevel inverter with photovoltaic MPPT control

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ABSTRACT

This article presents the five levels H-Bridge cascaded multilevel inverter with photovoltaic MPPT control. The power source is composed of photovoltaic panels used as DC inputs for the cascaded H-Bridge Multilevel Inverter. The present work aims to present a control strategy to produce the best output quality possible. The algorithm P&O extract from the panels the maximum power while the supervision system tends to control the DC levels in the CHMLI inputs. Each panel possesses its own MPPT module and the cascaded H-Bridge Multi-Level Inverter uses the modules as entries to produce a staircase waveform output. A simulation using matlab/simulink is realized to verify the system performance.

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1. Introduction

Photovoltaic energy is an important source of the renewable energy, it is an inexhaustible energy since it is derived from the sun's rays and, as such, it respects nature and the environment. It is a very reliable energy because there is no risk of rupture. In addition, the integration of photovoltaic panels in your home is simple and the installation is easy to use [1].

The cost of operation is low and maintenance is reduced. Nevertheless, photovoltaic energy is one of the major sources of renewable energy, it is an inexhaustible energy since it is derived from the sun's rays and, as such, it respects nature and the environment [3]. It is a very reliable energy because there is no risk of rupture.

In addition, the integration of photovoltaic panels in your home is simple and the installation is easy to use. The cost of operation is low and maintenance is reduced. However, the production of this is nonlinear and it varies according to the luminous intensity and the temperature.

Therefore, the photovoltaic panel operating point (PV) does not always coincide with power maximum point then uses a mechanism that allows search and track of power point maximum called "Maximum power point tracking" (MPPT) so that the maximum power is generated continuously.

As a result, several studies have focused on photovoltaic systems. They have tried to develop algorithms to extract the maximum energy converted by the panel and then that allows optimal operation of the photovoltaic system [1]. The PV module is essentially standard PV panel and DC-DC converter with MPPT Controller the

modular power electronics technology named multilevel inverter. There are three topologies commonly used at multiple levels of the inverter such as diode inverter, capacitor inverter flyer and multilevel inverter cascade.

Among the above cascaded topologies, H-bridge topology is the most suitable for the integration of renewable energy. It is used separately. Source DC can be powered from the PV panel [5] [6]. H-bridge in cascade the multilevel inverter is better than the other two types of multilevel inverter because of this requires less component, the cascade topology allows the use of DC source with different voltage values, same input voltage the output voltage obtained with H-bridge in cascade the multilevel inverter is twice as much as the output voltage with diode capacitor and flywheel capacitor and bridge power H cell connected in series to produce a high AC voltage.

A five-level modular H-bridge inverter cascade topology for the photovoltaic system connected to the three-phase network is presented in this document. The P & O algorithm extracts maximum power from the panels while the monitoring system tends to control the DC levels in the CHMLI inputs [5].

2. Photovoltaic power system

2.1. Photovoltaic cell model

A photovoltaic cell is a component made of semiconductor material that absorbs light energy and transforms it into electrical current. The operating principle uses the properties of light radiation absorption by semiconductor materials. To construct PV cells scientists relate to the physical properties of electrons subject to release from their original atoms when excited by photons in the solar radiation. The movement of these electrons forms a DC current which creates a DC voltage at the PV cell terminals. This phenomenon is called photovoltaic effect; Figure 1 presents a photovoltaic cell [1].

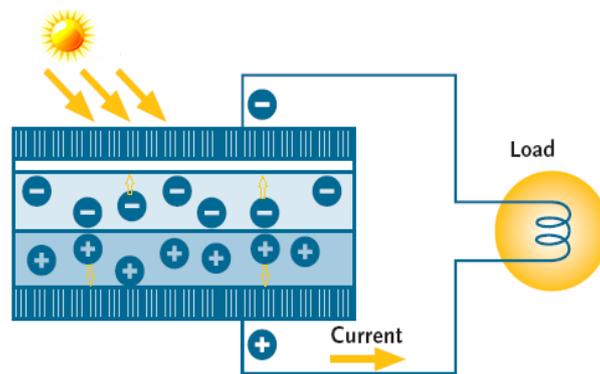


Figure 1. Presentation of a Photovoltaic Cell

In order to study a PV cell, many mathematical models may be used. Hereafter we study two equivalent models.

2.2. Double diode PV Cell model

In a double diode PV cell model two diodes D_1 and D_2 having respectively the saturation currents I_1 and I_2 are connected in parallel. The current source representing the PV Cell depends on sun's irradiation and produces a current I_{CC} . The series resistance R_S is an actual representation of the resistivity of the material and the semi-conductor-metal contact. The parallel resistance R_P on the other is a supplement shunt resistance. Figure 2 presents a two diodes model of a PV Cell.

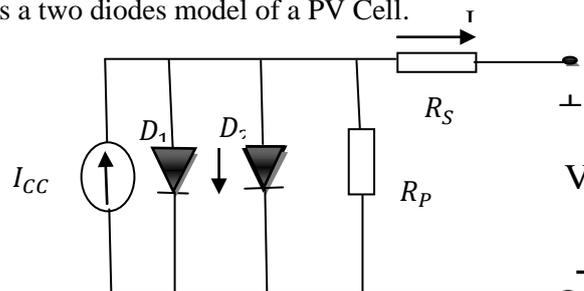


Figure 2. The double-diode PV cell electrical model

The current supplied by the PV Cell can be written as follows (Helali, 2012):

$$I = I_{cc} - I_1 \left[e^{\frac{q(V+IR_S)}{n_1KT}} - 1 \right] - I_2 \left[e^{\frac{q(V+IR_S)}{n_2KT}} - 1 \right] - \frac{V + IR_S}{R_p} \quad (1)$$

Different Parameters

- I_1, I_2 The diodes reverse current saturation D_1 and D_2
- K (1.381×10^{-23} J / K), the Boltzmann constant,
- T (K), the effective temperature of the cell,
- q (1.602×10^{-19} C), the charge of electron,
- n_1, n_2 The ideality factors
- I (A), the PV cell output Current,
- V (V), the module thermal voltage,
- R_P (Ω), the shunt resistor,
- R_S (Ω), the series resistance.

2.3. Single diode PV Cell model

The model Single diode is simple, it has a current source parallel to the diode. The accretion of the model that introduces a supplementary resistance shunt R_p exhibited in Figure3.

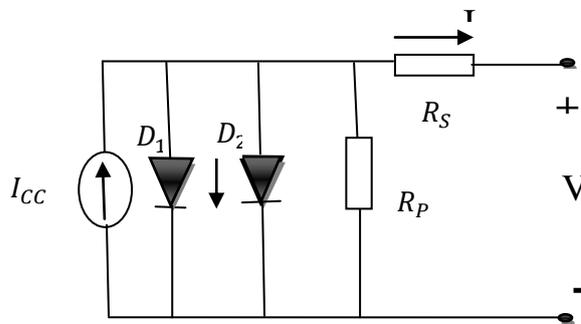


Figure 3. A-diode PV cell electrical model

The current supplied by the PV Cell can be written as follows (Pétion, 2009), (Cabal, 2008), (Cid Pastor, 2006) and (Helali, 2012):

$$I = I_{cc} - I_1 \left[e^{\frac{q(V+IR_S)}{n_1KT}} - 1 \right] - \frac{V + IR_S}{R_p} \quad (2)$$

2.4. Characteristic of the PV Cell

To analyze the both PV model behavior, a simulation is made in MATLAB To have a comparison of PV models and to show the effect of different parameters. The specifications are quoted in Table 1 and 2.

Table 1.The Cell module electrical characteristics data.

TypicalElectrical Performance	
Open Circuit Voltage	0.665 V
Short Circuit Current	5.75 A
Maximum Power Voltage	0.560 V
Maximum Power Current	5.35 A
Rated Power	3.0 W
Efficiency	20.0% minimum
Temperature Coefficients Voltage	-1.9 mV / °C
Temperature Coefficients Power	-0.38 % / °C

Table 2:Electrical characteristics data of panel module.

<p>Electrical Characteristics</p> <p>Measured under standard test conditions: 1000W / m² of sunlight, AM 1.5 and 25 ° C cell temperature</p>	
Rated power (+5% / - 3%) P	300 W
Voltage at maximum power V _{pm}	54,7 V
Current at maximum power I _{pm}	5,49 A
Open circuit voltage V _{CO}	64,0 V
Short circuit current I _{cc}	5,87 A
Maximum voltage of system IEC	1000 V
Temperature Coefficients Power	-0,38% / K
Temperature Coefficients Voltage (V _{co})	-176,6mV / K
Temperature Coefficients Current (I _{cc})	3,5mA / K
NOCT	45° C +/-2° C
Nominal value of standard fuses	15 A
Rolling currentlimit (3 strings / rows) IR	14,7 A

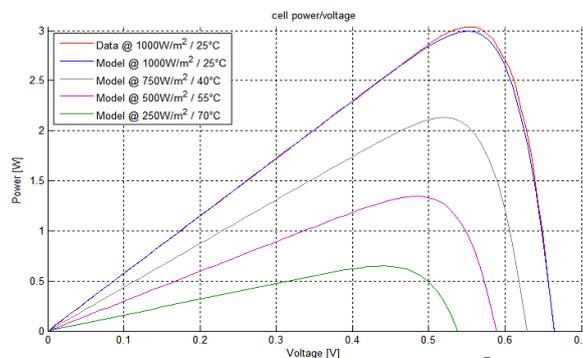


Figure 4. The model of Matlab I-V curves of different irradiation levels.

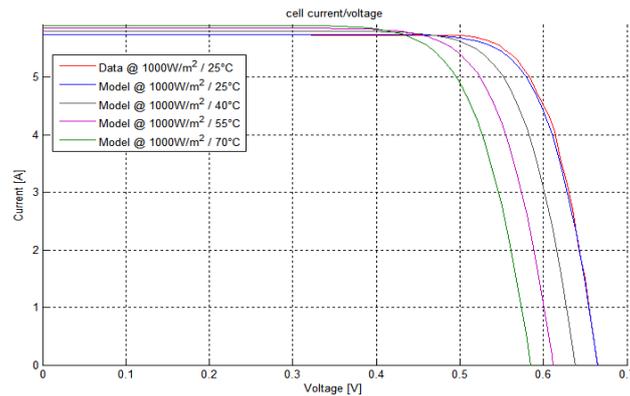


FIGURE 5. The model of Matlab I-V curves of different temperatures levels.

3. Maximum power point tracker

Maximum power point tracing (MPPT) The Power point tracker is a high frequency DC to DC converter .They took the input DC from the solar panels change it to high frequency AC, and convert it back down to a different DC voltage and current to exactly correspond t panels at batteries.

Therange of 20-80 kHz is usually assigned to the work of MPPT . The large frequency circuits advantagesis their abilityto be designed with a large efficiency transformers and small components[1] [4].

Many methods of finding the MPP had been published. These techniques are different in various aspects like as complexity ,cost,convergence speed,required sensors, tracking while irradiation change of temperature, effectiveness range, correct, needed hardware at thepopularity or implementation , among others. A review completed of 19 algorithms MPPT is found at[7].

The algorithms InCond and P&O are the most frequent.

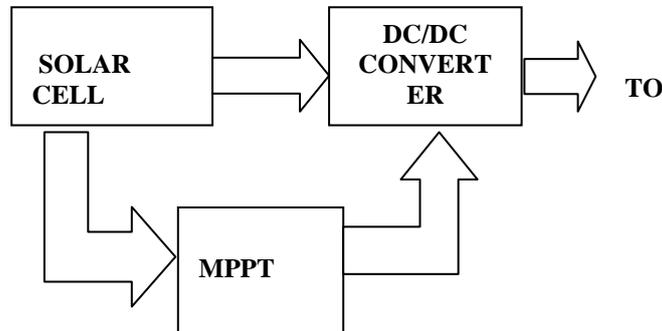


Figure 6.Block diagram of Typical MPPT system.

3.1. P&O algorithm for MPPT control

In renewable energy, optimization algorithms of the MPPT problem are used to increase energy transformation. Among the much used algorithms, we have the P&O, used by many authors. Its few code lines and simplicity make it easy to deploy[9].

The disadvantage of this algorithm is that in some cases, especially under partial shading, the algorithm cannot find the maximum power point. As it is a widely used algorithm, it is a good idea to implement it and take it as a reference point.

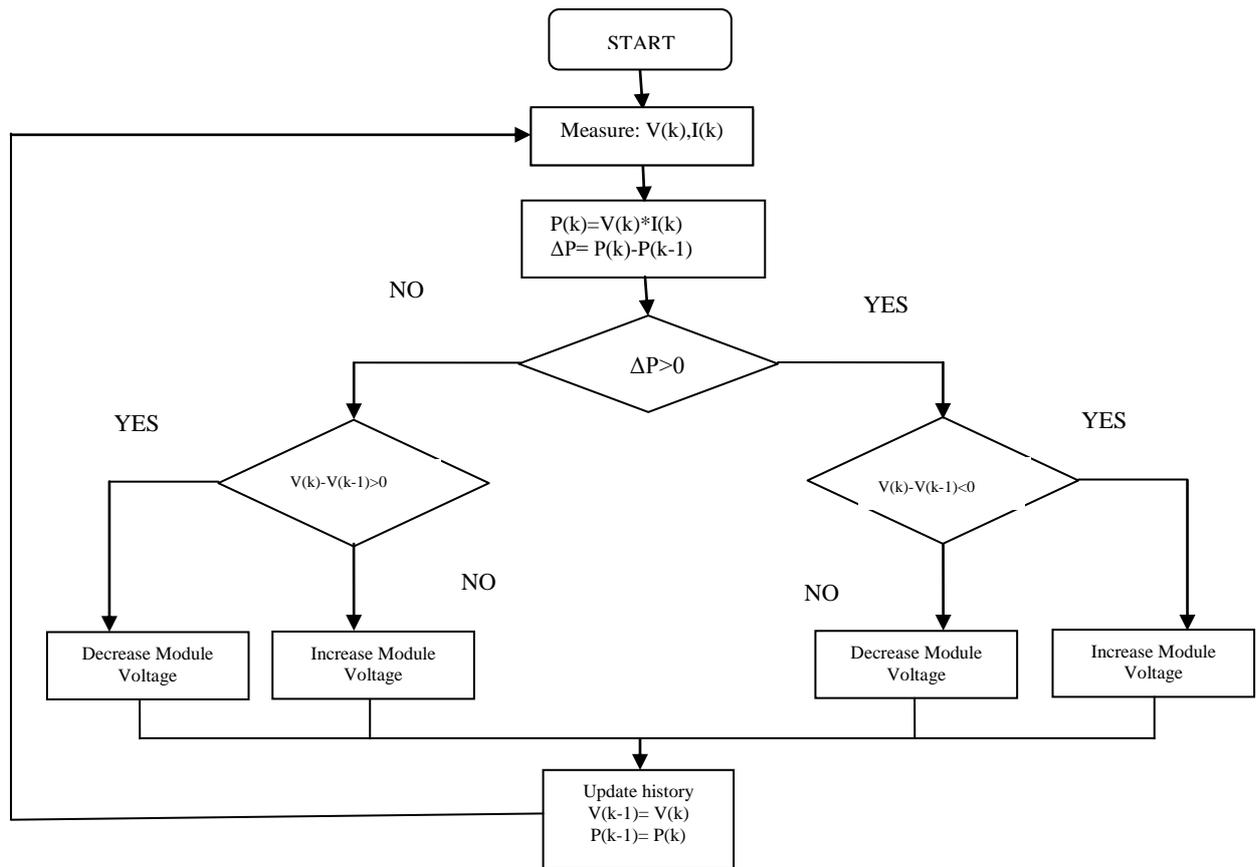


Figure 7. the P&O algorithm Flowchart .

3.2. Simulation of the PV system for variation of temperature or irradiance

The photovoltaic system studied is composed of the PV panel, the MPPT control based on P&O algorithm, a DC-DC boost converter and a resistive load as shown in Figure 8.

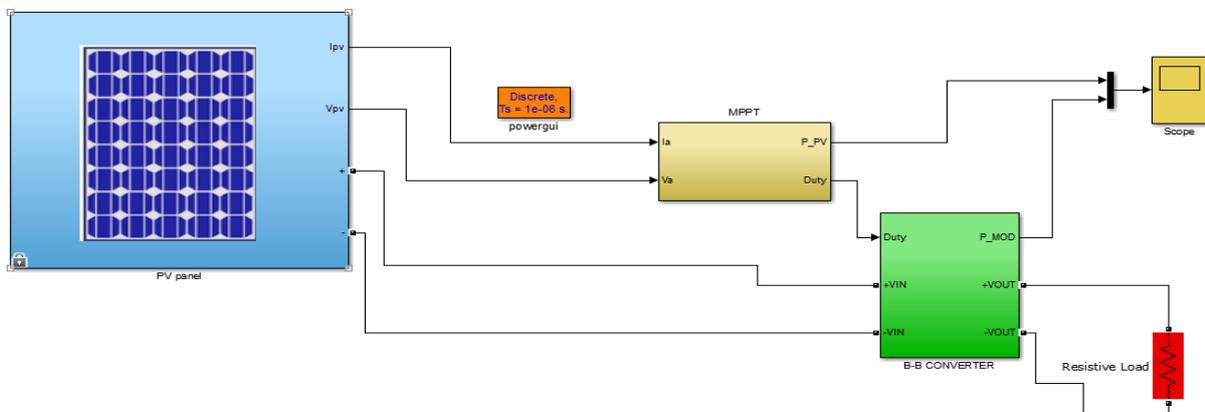


Figure 8. Photovoltaic system

The simulation in matlab-simulink results are given by the following figure:

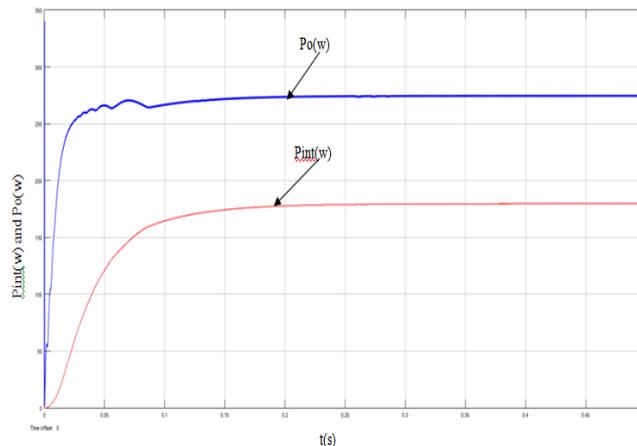


Figure 9. $P_{in}(t)$ & $P_o(t)$.

3.3. Analysis of the simulation results

In this section, we carry out the simulation results for the both variation $P_{in}(t)$ & $P_o(t)$. La figure 9 shows the power with and without MPPT regulator while this technology offers an appreciable power gain of the order of 20% to 30%.

4. DC/AC multilevel conversion

4.1. Generalities about the multilevel inverter

Two categories of multilevel inverter are currently listed. The first groups the main inverters into three groups: 1) Loop diode inverters (in English clamping diodes called diode clamp) Neutral Point Clamped (NPC) and Multiple Point Clamped (MPC)[8].

2) Float capacitor inverter [or Flying Capacitor (FC)]

3) H-bridge cascade bridge inverter.

The second category of multilevel inverters includes the hybrid assemblies of inverters of the first category [5]. Thus, among others we can mention:

1) NPC in cascade (CDC),

2) H-bridge in cascades (CMH),

3) NPC and H-bridge cascading (CDCH)

4.2. H-Bridge Multilevel Inverters

The first inverter model was the bridge inverter H (H-bridge), which appeared in 1975.

Advancement of multilevel inverters was due to the series H cascaded bridge model. TheThe first H bridge inverter application was for plasma stabilization in 1988 [6]. The bridge inverters outputs are in series so that voltage wave synthesized is the output sum voltages. The major advantage of this approach is that the number of steps on the pattern of the voltage can be increased without any addition of new components. The use of serial power conversion cells allows increasing the number of voltage and power level of the converter. But the disadvantage major feature of this topology is the large number of isolated DC voltages required for each bridge [5].

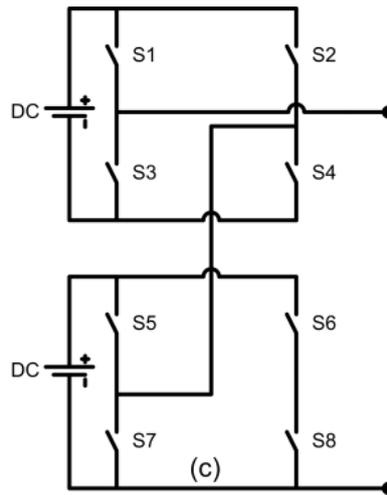


Figure 20. Inverter H-bridge 5 levels.

For an inverter with k levels, the number of elements constituting its topology: s for isolated DC sources, m for the power transistors are given, for each phase, by the following relationships:

$$s = (k - 1) / 2 \quad (3)$$

$$m = 2 * (k - 1) \quad (4)$$

However, the cells can be powered by phase shifted transformers medium voltage to provide higher power. In this case, if n_s is the number of independent sources, the number of levels of the output voltage n_m is given by the equation below:

$$n_m = 2n_s + 1 \quad (5)$$

4.3. Simulation and analysis of the CHMLI model study

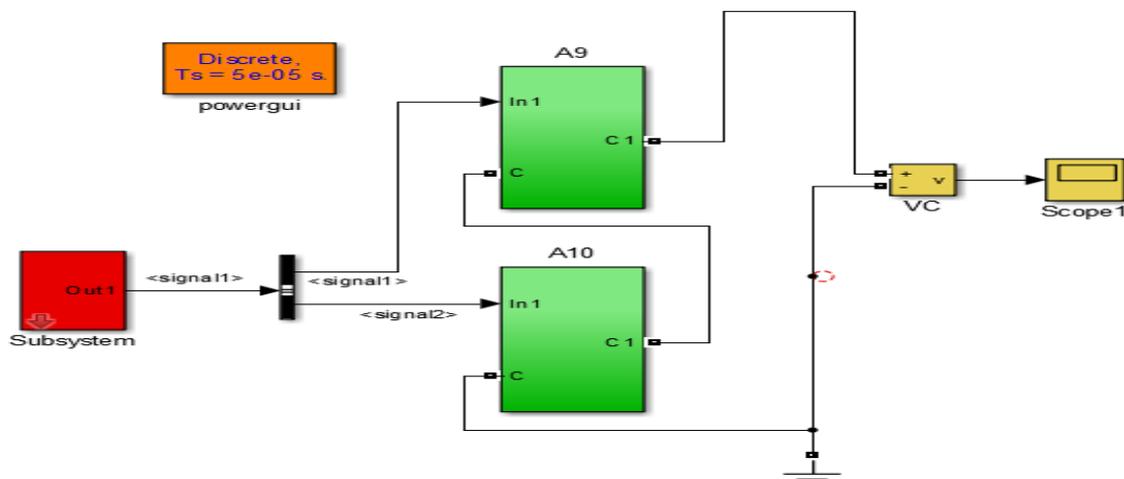


Figure 31. The multilevel inverter cascaded H-Bridge

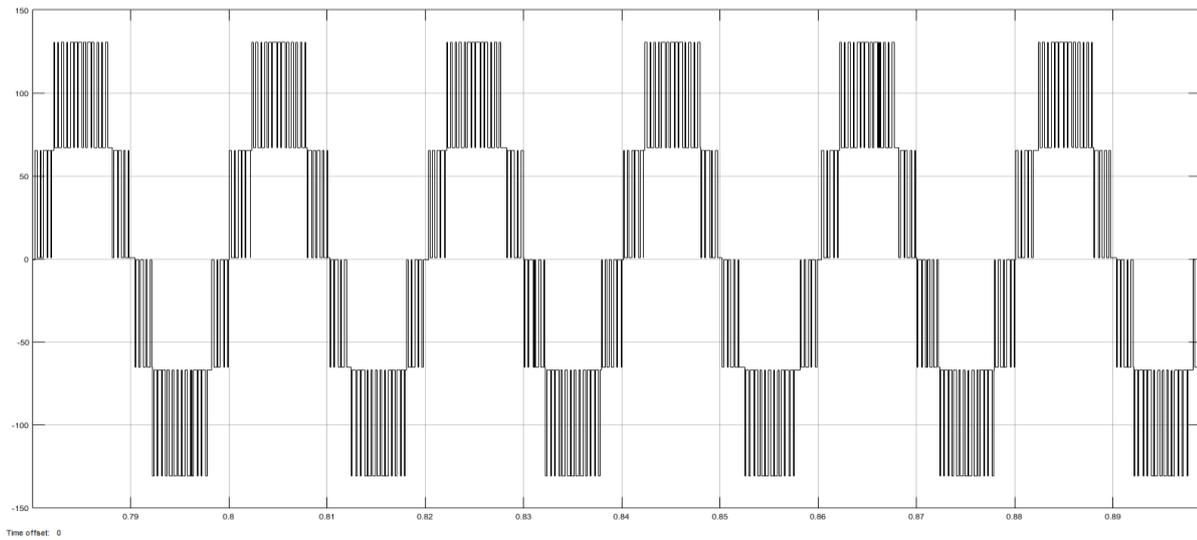


Figure 42. Voltage output of the 5 levels cascaded H-Bridge multilevel inverter.

This Figure gives the voltage output of CHMLI before each balancing procedure.

5. Simulation and analysis of the PV generator with MPPT and CHMLI

5.1. Model of the PV with MPPT algorithm P&O and CHMLI

Multiple PV arrays connected in series before DC-DC converter by a single MPPT controller.

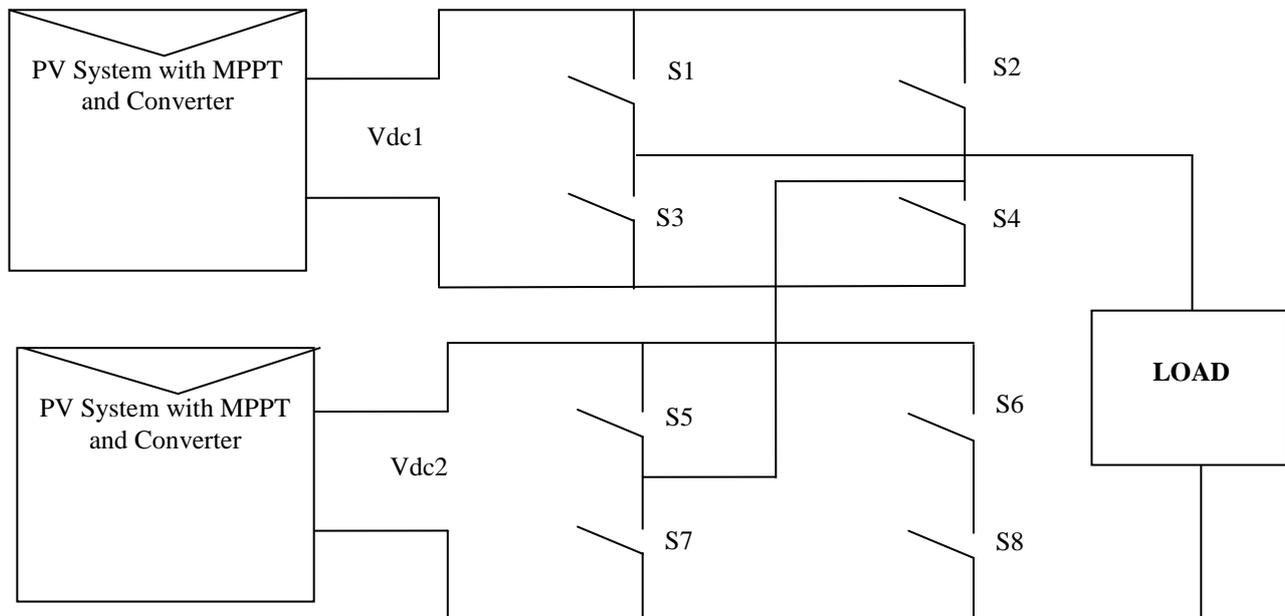


Figure 53. Integration PV System with MPPT and CHMLI

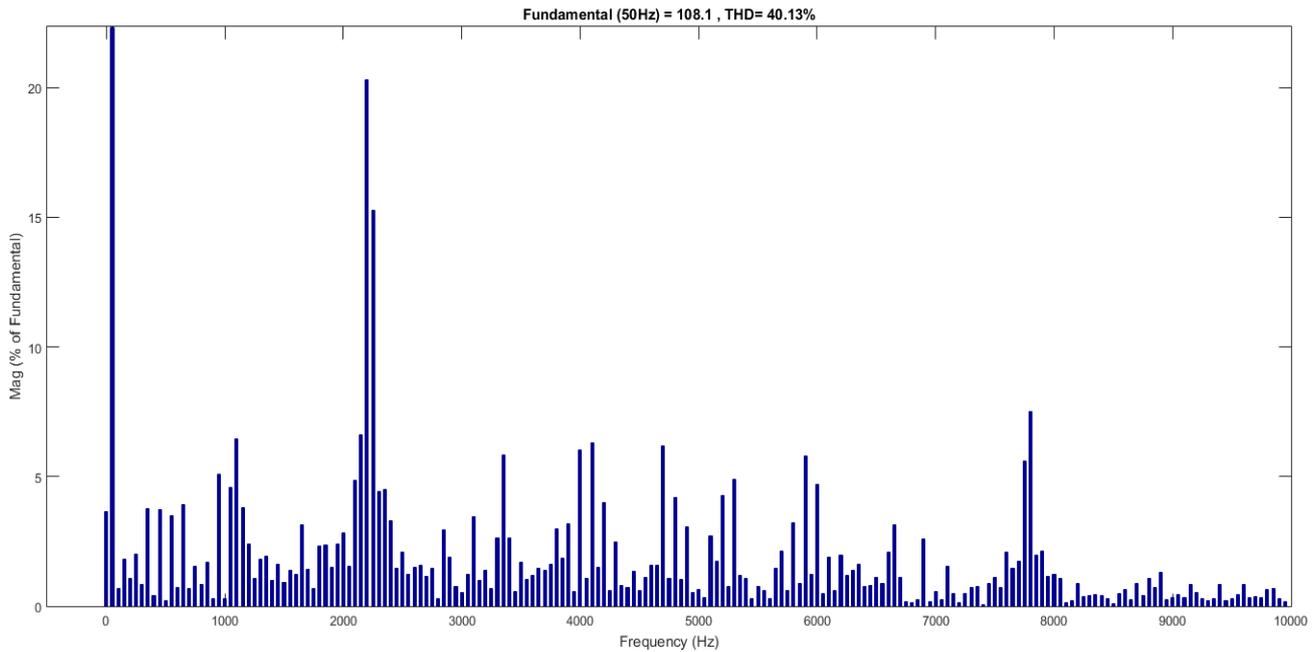


Figure 64. Output voltage spectrum analysis of the 5 levels CHMLI with MPPT

5.2. Analysis of the simulation results

The figure gives the spectrum voltage analysis; we recorded a 32.14% THD. We observe that before the use of the MPPT the CHMI multilevel inverter works randomly with the DC inputs provided by the PV which generates a low efficiency. While with the application of the MPPT to CHMLI, its last works at the best possible power point, this implies better performance and optimal operation using resistive loads.

6. Conclusion

In this work, we proposed the design and simulation of photovoltaic systems PV, MPPT and CHMLI. We have described the photovoltaic PV module, these characteristics and the simulation of the I-V curves of the model. We presented the role of the MPPT technique with the P & O algorithm, thus the simulation in the Matlab-simulink environment of the MPPT and a multilevel H-Bridge inverter in cascade of five levels then make the simulation of the two montages. Finally we extracted the curves and we analyzed them.

In a second step, we integrated PV, MPPT and CHMI systems with a resistive load. The results of the simulation showed that the system operates at its maximum power in a satisfactory manner.

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