

Multi-Objective Artificial Bee Colony Algorithm to Estimate Transformer Equivalent Circuit Parameters

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Article Info

Article history:

Received May 23th, 2017

Revised Aug 18th, 2017

Accepted Oct 18th, 2017

Keyword:

Multi-objective artificial bee colony algorithm
Multi-objective optimization
Transformer parameter estimation

ABSTRACT

Real world problems such as scientific, engineering, industrial problems are in the form of the multi-objective optimization problems. In order to achieve optimum solutions of such problems, multi-objective optimization algorithms are utilized. In this study, the problem is estimation of single-phase transformer parameters which is one of the engineering problems. This estimation is provided by artificial bee colony (ABC) algorithm. ABC is developed as a metaheuristic method and simulates foraging of bees. Since the problem is a multi-objective optimization problem, multi-objective ABC (MOABC) is proposed to estimate parameters in the study. This study aims to estimate equivalent circuit parameters using current and voltage values at any known load. Through algorithm, difference between actual and estimated parameter values that is the error has been tried to minimize. The successful results show that the proposed method can be used for a single-phase transformer parameters estimation.

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1. Introduction

Many engineering problems in the world have more than one objective. The main goal of the problems is to find optimum solutions for all objectives simultaneously. For this reason, the results are a set of optimum solution. In multi-objective problems (MOPs), problem solvers suggest this set of solutions to decision makers generally and decision makers decide an optimum solution from the set according to importance of the problem type. The set of optimum solutions is named as Pareto-optimal set [1]. Pareto-optimal set stores solutions which are not worse than each other. Namely, a Pareto-optimal solution is better than at least one of all objectives. These solutions are also named as non-dominated solutions [1]. This domination term is described as detailed in Section II. At this point, at the stage of proposing set of solutions, multi-objective optimization algorithms (MOAs) are utilized. In order to solve MOPs, proposed optimization algorithms are generally meta-heuristic algorithms. For instance, Multi-objective genetic algorithm is proposed to solve many MOPs such as flow shop scheduling [2] and fuzzy rule selection [3]. Multi-objective particle swarm optimization is also proposed to solve MOPs such as job-shop scheduling problem [4] and electromagnetic absorber design [5].

This study is focused on parameter estimation problem of a single-phase transformer being one of the engineering problems. Transformers are used as an electric machine to convert energy from one voltage to another voltage. In order to estimate transformer parameters, two experimental tests and some computations

are required. This study provides parameters without any experimental test using proposed method with known current and voltage values at any known load.

So far, identification of the transformer parameter is realized as single optimization problem as [6], [7], [8]. However, in non-convex multi-objective optimization problems, results cannot be reached some optimum solutions when objectives of the problem are combined to do single objective problem [1]. Because of this reason, the transformer parameter estimation problem is solved as multi-objective optimization problem using Multi-Objective Artificial Bee Colony algorithm (MOABC) in this study. The algorithm is a population-based and stochastic optimization method. Foraging of real honey bees is simulated by the ABC. The original version of the ABC is for single optimization problems. Therefore, MOABC algorithm is utilized to identify transformer parameter being multi-objective problem.

In this paper, firstly described multi-objective optimization problems; then MOABC algorithm is described in detail; then introduced the problem and implementation of the MOABC to the problem. Finally, reported experimental results and conclusion.

2. Material and Methods

2.1. Multi-Objective Optimization Problems

MOPs involves more than one objective to find minimum or maximum solutions. In single objective optimization, there is sightful and only one purpose: to be minimized or maximized. On the contrary, in MOPs, there are conflicting objectives in some cases.

General form of MOPs can be expressed as (1), (2) and (3);

$$x = \{ x_1, x_2, \dots, x_D \} \quad (1)$$

$$\text{Minimize or Maximize } f(x) = \{ f_1(x), f_2(x), \dots, f_m(x) \} \quad (2)$$

$$s. t. g_p(x) \leq 0; \quad p = 1, 2, \dots, P$$

$$h_n(x) = 0; \quad n = 1, 2, \dots, N \quad (3)$$

where x is a solution vector, D is dimension of the problem. Also, $f(x)$ is called objective vector, g and h functions are constraints of the problem.

In MOPs, unlike single objective problems, the optimum solution is a solution set. Because, the solutions are trade-off and are known as Pareto-optimal set. This set refers to Pareto dominance [9], [10], [11]. The term of dominance is frequently encountered term in MOPs. The states of dominance can be expressed by the following conditions [1];

If the solution x_1 dominates x_2 , both case 1 and case 2 are verified;

Case 1: The objective values (f_1 and f_2) are compared and the solution x_1 is found no worse than the solution x_2 for all objective.

Case 2: At least one objective, the solution x_1 outperforms the solution x_2 .

If the solution x_1 dominates all other solutions in the population, it is called non-dominated solution. Desired of MOPs, the solution set consists of non-dominated solutions. Representing of Pareto-optimal set and concept of dominance are illustrated as Fig. 1 for two objectives (f_1 and f_2) to be minimized [12].



Figure 1. (a) Representing of Pareto-optimal set

(b) Concept of Dominance

To find optimal set of MOPs, the algorithm has some mechanisms. Two important parts of them are External Archive and Update External Archive.

2.1.1. External Archive (EA)

In MOPs, despite of the fact that more than one objective, the algorithms generate an optimal solution set. The set maintains non-dominated solutions. To store these solutions, external archive can be used as [13], [14]. The archive is initialized in the first phase. Then, objective values of the solutions are compared and non-dominated solutions are stored in the EA. Also, EA is updated in every cycle.

2.1.2. Update External Archive

In every cycle, the EA is updated. In this paper, updating procedure is associated with domination procedure. Every solution in population of the algorithm is respectively compared with the EA solutions. The solution in the EA dominated by population member is removed from the archive, and the dominant solution of the population is added into the EA. Not only dominant solutions are added, but also non-dominated solutions in the population are joined into the EA.

2.2. Multi-Objective Artificial Bee Colony Algorithm

The basic artificial bee colony algorithm (ABC) has been proposed by Karaboga [15] in 2005. ABC is a nature-inspired algorithm. In nature, honey bees search food sources and when they find any source, they share the knowledge about the source with the other bees by dancing. Inspired by this communication, ABC algorithm is developed. Employed, onlooker and scout bees are the types of artificial bee in the algorithm. Also, initially, the initial parameters of colony size, maximum cycle and limit value are set. Limit value is the abandonment value of the food source. Initial population is generated by randomly and other phases are follows;

Employed bees: This type of bees calculates nectar amounts of the neighbor food sources. After comparing existing source and neighbor source, employed bees select the better source.

Onlooker bees: Using the information about the quality of food sources, onlooker bees interpret the sources. Then, all onlooker bees choose a food source and are fed.

Scout bees: In the ABC, employed bee turns into a scout bee when the food source is consumed (reaches the limit value).

The basic form of the algorithm is introduced for single optimization problems. In this study, the optimization problem has three objectives to be minimized. Therefore, the focus of the study is multi-objective ABC (MOABC) algorithm.

In MOABC, defining initial values of the food sources are the same with the basic ABC. It can be showed as (4);

$$x_{ij} = x_j^{\min} + rand(0,1)(x_j^{\max} - x_j^{\min}) \quad (4)$$

x_{ij} is j . dimension of i . food source where $i = (1, \dots, FN (Food Number))$ and $j = (1, \dots, D (Dimension))$. The maximum and minimum bounds of the dimension is respectively x_j^{\max} , x_j^{\min} .

One of the most important modification in MOABC is to determine neighbor food source. In the algorithm, each employed bee, which performs this part, utilizes EA member specified randomly to optimize its solution. It can be defined the following equation (5);

$$v_{ij} = x_{ij} + \phi_{ij}(x_{ij} - \mathbf{ExAr}_{kj}) \quad (5)$$

V is neighbor solution of X_i and j is the random parameter of X food source, and k is the random member of the EA. ϕ_{ij} is a value between $[-1,1]$. Whenever the neighbor solution is determined, space bound is controlled. If a parameter exceeds the bounds, the parameter pulls the limits.

After determining the parameters, fitness values for all objectives of the two solutions are compared. This process uses greedy selection mechanism. Namely, the solution dominating the other solution is selected. If the selected solution is neighbor solution, then the abandonment value of the source is reset. Vice versa, abandonment value of the source is incremented. Fitness value is determined as (6);

$$fitness_i = \begin{cases} 1/(1 + f_i) & , f_i \geq 0 \\ 1 + abs(f_i) & , f_i < 0 \end{cases} \quad (6)$$

$fitness_i$ is fitness value of i . food source for minimization problems. If the problem is maximization, f_i denotes the fitness value.

After employed bees, new tasks are realized by onlooker bees. The mission is to choose a food source to optimize the solution using tournament selection for each onlooker bee. In tournament selection, two random food source is chosen from the population and onlooker bee choses the solution has better fitness value, and the neighbor food source is determined as employed bee part. Then, greedy selection is applied in this part, too. Abandonment value is updated according to which source is selected.

The last type of bee is scout bee. Scout bee part is completely as basic ABC. If a food source reaching the limit value, then the food source is exhausted. The parameters of the food source are randomly determined again and abandonment value is reset.

After completing all bee parts, updating EA procedure occurs. Each bee in the population is compared with the EA members according to fitness values. If the solution x_i dominates the member of EA, the EA member is removed and the solution x_i is inserted into the EA. If the solution x_i and EA member are non-dominated solutions, then the solution x_i is inserted into the EA.

Pseudocode of MOABC algorithm can be expressed as Fig. 2.

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Initialize the food source with random solutions
Evaluate fitness values of all objectives
Generate External Archive (EA) from non-dominated solutions in the population
While (stopping criteria not met)
  For each employed bee
    Choose randomly a parameter
    Choose randomly a solution as a neighbor from EA members
    Calculate fitness value of new solution
    Apply greedy selection on the solutions based on Pareto-optimality
  End for // employed bee part
  For each onlooker bee
    Choose a solution from the population using tournament selection
    Choose a neighbor solution as employed bee
    Calculate fitness value of new solution
    Apply greedy selection on the solutions based on Pareto-optimality
  End for // onlooker bee part
  If a food source reaching limit value
    Generate new solution randomly for the food source
  End if // scout bee part
  // Update Archive Procedure
  For each bee in the population
    Compare with EA members and solution of the population based on Pareto-optimality
    If the solution of the population dominates the member of EA
      Remove the member of EA
      Insert the solution of the population into EA
    End if
    If the member of EA and solution of the population are non-dominated solutions
      Insert the solution of the population into EA
    End if
  End for
End while

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Figure 2. Pseudocode of the MOABC algorithm

3. Transformer Equivalent Circuit And Parameter Estimation Using MOABC

Transmission of electrical power from the place of production to other regions is provided by alternative current. Due to the high voltage of the alternating current electrical power, transformers are used. A transformer provides to transform from the high voltage of electrical power to low voltage or vice versa. While doing this transformation, no change in the frequency. A transformer structure consists of two windings being called primary and secondary winding. The transformers can be classified as single-phase and poly-phase transformers. In single-phase transformers, primary winding is for input signal with single phase, and secondary winding can be one or more according to aim. On the other hand, in poly-phase transformers, number of primary winding is two or more, and secondary winding can be one or more according to aim. Poly-phase transformers are often wrapped in three phases, and also this information can be found in detail in [16].

In this study, single-phase transformers are focused on and the equivalent circuit of a single-phase transformer is illustrated as Fig. 3. When estimation of the transformer parameters is examined, two tests are required: no-load and short-circuit operation. These tests are examined in detail in [16]. Owing to this study, only from current and voltage at any known load, the transformer parameters are obtained without any test. Each equation of transformer parameters is obtained from Kirchhoff's circuit laws and thereby three objectives of the problem are identified.

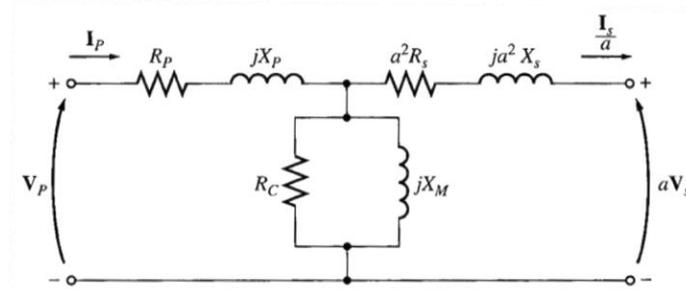


Figure 3. Equivalent transformer circuit referring to the primary

where R_p is primary winding resistance, X_p is primary winding leakage reactance, V_p is primary voltage, I_p is primary current, a is transforming ratio, R_s is secondary winding resistance, X_s is secondary winding leakage reactance, I_s is secondary current, V_s is secondary voltage, R_c is resistance of core and X_m is magnetizing reactance in the Fig. 2.

$$Err_1 = ||I_p| - Act_{I_p}| \quad (7)$$

$$Err_2 = ||I_s| - Act_{I_s}| \quad (8)$$

$$Err_3 = ||V_s| - Act_{V_s}| \quad (9)$$

where Err_1 is the error of the I_p , Err_2 is the error of the I_s' (I_s/a), Err_3 is the error of the V_s' (aV_s). I_p , I_s and V_s are obtained by Kirchhoff Circuit Laws.

In this stage, MOABC creates randomly initial parameters which of R_p , X_p , R_s' (a^2R_s), X_s' (a^2X_s), R_c and X_m and calculates fitness values of the objectives benefiting from the parameters. Then, non-dominated solutions are stored in the EA. While stopping criteria is not met, each bee tries to improve the solutions. When reaching to stopping criteria, MOABC determines Pareto-optimal solutions of the problem in the archive. According to the Euclidean distance method, the best solution is selected through the EA members. Finding minimum solution in the EA is associated with parameters of the problem.

4. Experimental Results

MOABC is used to estimate transformer parameters according to current and voltage at any known load in this study. The performance of the MOABC is investigated in two different load.

In Case I, the transformer parameters (R_p , X_p , R_s' , X_s' , R_c and X_m) are determined using MOABC at a Z_{L1} load ($Z_{L1}=50+i30\Omega$). Actual data can be obtained by experimental tests which are no-load and short-circuit operation. This study assumes that the actual parameters are already known. Then, current and voltage (I_p , I_s' and V_s') are calculated according to estimated parameters. Actual data, estimated data and error rate are

showed in Table I. The results show that proposed method is very satisfied for estimation parameters of the single-phase transformer.

This study is for estimation of the parameters even if at different load operations. Therefore, the results are demonstrated at the another Z_{L2} load ($Z_{L2}=22.3607\Omega$) in Case II as Table II. The results show again superior performance of MOABC algorithm to estimate same parameters at another load.

Table 1. Case I: Estimated Parameters of the Single-Phase Transformer obtained by MOABC algorithm at Z_{L1} load.

Parameters and Transformer Data	Actual Data	Estimated Data by MOABC	Error (%)
Rp (Ω)	1	1.054	-5.4
Xp (Ω)	2	1.978	1.1
Rs' (Ω)	1.4	1.433	-2.36
Xs' (Ω)	1.8	1.870	-3.89
Rc (Ω)	6400	6339.49	0.95
Xm (Ω)	1100	1092.50	0.68
Ip (A)	3.65	3.6500	0
Is' (A)	3.50	3.6279	-3.65
Vs' (V)	205.37	211.42	-2.95

Table 2. Case II: Estimated Parameters obtained by MOABC at Z_{L2} load.

Parameters and Transformer Data	Actual Data	Estimated Data by MOABC	Error (%)
Rp (Ω)	1	1.2320	-23.2
Xp (Ω)	2	2.1693	-8.47
Rs' (Ω)	1.4	1.1617	17.02
Xs' (Ω)	1.8	1.6326	9.3
Rc (Ω)	6400	6442.27	-0.66
Xm (Ω)	1100	1088.43	1.05
Ip (A)	8.47	8.4648	0.06
Is' (A)	8.45	8.4514	-0.02
Vs' (V)	202.27	202.33	-0.03

5. Conclusion

This paper is focused on MOABC algorithm to estimate single-phase transformer parameters via current and voltage values at any known load. ABC algorithm simulates honey bee behavior. The reason for choosing this algorithm is simple implementation and minimum control parameters. In optimization process, the algorithm tries to minimize error between actual and estimated data. Proposed MOABC uses Pareto-optimality concept to achieve optimum solutions of the problem. Through the non-dominated solutions, one optimum solution is selected using Euclidian distance method. The results of the proposed method show that using MOABC algorithm to estimate transformer equivalent circuit parameters very satisfactory results is obtained.

Acknowledgements

This study is supported by Academic Staff Training Program of Selcuk University, Konya, Turkey. The Project number is 2015-ÖYP-005.

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